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Monday, 23 March 2020 Tuesday, 24 March 2020 Wednesday, 25 March 2020 Thursday, 26 March 2020 Session 1: Avatar - Appearance Monday, March 23, 11:00 AM - 12:30 PM, Track 1 (Big Room 1) Effects of Locomotive Style and Body Visibility through Avatar Youjin Choi (KAIST), Yongmi Lee (KAIST), Sung-Hee Lee (KAIST) Abstract Conference: Teleprompter Allow users in different environments to interact with each other. However, in order to increase the effectiveness of these interactions, avatar movements need to be adjusted accordingly to take account of differences between user environments. Several movement styles can be used to achieve this speed change. This article discusses how different styles of avatar movement (speed, agility and sliding), body visibility levels (whole body and head-to-knee), and views (front and side views) affect human perceptions of natural movement, similarity with the user's locomotive and the degree of preservation of the user's intent. Manipulation of dolls in VR Michael Nichet (Georgia Institute of Technology, USA), Pierce McBride (Georgia Institute of Technology) Abstract: Archival stage objects aimed at applying and preserving puppet theater as a creative practice in VR. It includes 3D scanning and an interactive design for capturing dolls and their various control schemes from the archives of the Puppet Arts Centre. This document takes into account their design and execution in the VR-created dollhouse. It focuses on evaluation (n=18), comparing the interaction between non-experts and expert puppeteer. The data initially showed small differences, but a more detailed discussion shows different quality assessments of the puppet environment that support its VR value. The results suggest successful creative activation, especially among experts. The self-waiting effect of virtual reality followers Mar Gonzalez-Franco (Microsoft Research), Brian Cohen (Microsoft Research), Eyal Ofek (Microsoft Research), Dalila Buren (Tohoku University), Antonella Masselli (Microsoft Research) Abstract: When you embody a virtual avatar in immersive VR apps, users are usually and feel in control of taranian movements. However, there are situations in which technology can reverse this connection, so an embodied avatar can affect the user's engine behavior without users noticing it. This is shown in retargeting applications for action and motor contagion experiments. This is where we discuss the effect of the S dirham. We review previous evidence and present new experimental results showing how, when the virtual body does not overlap with their physical body, users tend to unknowingly follow their avatar, filling the gap if the system allows it. Effects of capture avatars on social presence in immersive virtual environments SungIk Cho Cho University, South Korea), Seung-wook Kim (Korea University, South Korea), JongMin Lee (Korea University, South Korea), JeongHyeon Ahn (Korea University, South Korea), JungHyun Han (Korea University, South Korea) Abstract Conference: Recent achievements in 3D reconstruction and tracking technologies have made possible volume capture of the human body and performance in real time. However, in the field of human-computer interaction, no user survey works made with such volume capture avatars were reported. This article explores how a voluminous capture avatar affects users' sense of social presence in immersive virtual environments. Two experiments were done where an actor's volumetric capture avatar was compared to the actor captured in a 2D video and another 3D avatar obtained by pre-scanning the actor. The results of the experiment show that new volume capture techniques can be an attractive tool for many XR applications. Data modeling drive dominance traits for virtual characters using Tanta Analytics Tanmai Randaan (University of North Carolina), Aniket Bera (University of North Carolina), Emily Cuban (University of Tilburg), Kurt Gray (University of North Carolina), Dineto Manucha (University of Maryland) Abstract Newspaper: We present a data-driven algorithm to generate gaits from virtual characters with different dominant traits. Our formulation uses a user survey to create a data-driven dominance comparison between gait and dominance labels. We use our dominance to generate walking gaits for virtual characters who exhibit different dominant traits while interacting with the user. Furthermore, we extract gait characteristics based on known criteria in visual perception and psychology literature that can be used to identify the levels of dominance of each walking gait. We validate our mapping and perceived dominant traits from a second user survey in a fascinating virtual environment. Our gait classification algorithm can classify gait qualities with ~73% accuracy. We also present to you an application of our approach that simulates the interpersonal relationship between virtual characters. As far as we know, ours is the first practical approach to classifying gait dominance and generating dominance in virtual characters. Session 2: 3DUI - Selection/Study on Monday, March 23, 11:00 - 12:30, track 2 (Great Room 2) study of Bubble ray casting mechanism to improve the acquisition of 3D purpose in virtual reality Yiqin Lu (Department of Computer Science and Technology Tsinghua University; Key Laboratory of Universe Computers, Ministry of Education, Chun Yu (Department of Computer Science and Technology, Tsinghua University; Main Laboratory of Changing Computers, Ministry of Education, China), Tsinghua University; Key Laboratory of Penetrating Computers, Ministry of Education, China) Abstract at the conference: We are exploring a bubble mechanism for radiation work that dynamically resizes the beam selection range to acquire 3D target targets in virtual reality. Bubble mechanism identifies the target closest to the beam, with which users do not have to shoot exactly through the target. We design the selection criterion and visual feedback of the balloon and conduct two experiments to evaluate radiation processing techniques with a balloon mechanism in simple and complex tasks for acquiring 3D target objects. The results show that the mechanism of the balloon significantly improves radiation emanation in both performance and preferences, and the Bubble Ray technique with angular distance determination is competitive compared to other techniques for acquiring target technologies. Improving awareness obstacles to improving interaction in virtual reality Ivan Valentini (University of Genoa), Giorgio Ballestin (University of Genoa), Chiara Bassano (University of Genoa), Fabio Solari (University of Genoa), Manuela Chessa (University of Genoa) Abstract: Immersive VR is experienced through HMDs, while the user is physically present in a real, cluttered environment. We present a method for creating a virtual scenario composed of virtual objects with the same spatial occupancy of the respective real ones. The real scene is captured to detect the position and boundaries of a box of objects and obstacles, then virtual elements of similar sizes are added. Two different techniques for detecting and grouping the structure are described and compared, taking into account also the sense of presence of users in relation to the standard technique. The method allows us to maintain real environmental awareness while maintaining a high level of immersion and sense of presence, and to achieve increased virtual interaction. Slicing volume: Hybrid 3D/2D multipurpose technique for selecting dense virtual environments Roberto A. Montano-Murillo (University of Sussex, Brighton, United Kingdom), Kyong Nguyen (Adobe Research, San Francisco, California, United States), Rubayah Habib Kazi (Adobe Research, In this paper, we offer Cut-Volume, a hybrid selection technique that allows both 3D mid-air interaction, and a metaphor for a 2D pen and tablet in VR. We evaluated our approach in highly clogged selection tasks and showed that our hybrid technique significantly improves the accuracy of selection compared to medium-selection of air only thanks to the added haptic feedback provided from the surface of the physical tablet. ENTROPIA: To the endless Surface Haptic displays in virtual reality using Rotating Props Victor Mercado (INRIA Rennes), Maud Marchal (INRIA Rennes), Anatole Lécuyer (INRIA Rennes) Journal Abstract: In this article, we suggest an approach to endless surface display. Our approach, called EN-type RRotating Propi approach (ENTROPIA), is based on cylindrical spinning of a feather attached to the robot's final effector, serving as a haptic meeting-type display (ETHD). This type of haptic display allows users to have unlimited, free surface contact provided by a robotic device so that users can touch the surface to touch. In our approach, the feeling of touching a virtual surface is given through an interactive technique that pairs with the sliding movement of the prop under the finger of users by tracking the location of their hands and establishing a path to be explored. This approach allows great movement for greater surface rendering, allows for very textured haptic feedback and takes advantage of the ETHD approach, which introduces great motion and drag/friction sensations. As part of our contribution, proof of concept is designed to illustrate our approach. A user survey was conducted to assess the perception of our approach, showing a significant performance to transform the feeling of touching a large flat surface. Our approach can be used to build large haptic surfaces in applications such as fast prototyping for automotive design. Session 3: View and Attention: Inauguration on Monday, March 23, 11 a.m. to 12:30 p.m., Record 3 (Studio 1): Anticipating CN-based gas in dynamic scenes Zhiming Hu (Beijing University, China), Shen China), Congyi Zhang (University of Hong Kong, China), Kangrui Yi (Beijing University, China), Gupping Wang (Beijing University, China), Dinesh Manocha (University of Maryland, USA) Journal Abstract: We conduct novel analyses of user behavior in the eyes of dynamic virtual scenes and, based on our analysis, present a new CNN model called DGaze for gaze in HMD-based applications. For the first time, we collect eye tracking data from 43 users in 5 dynamic scenes under free viewing conditions. We then perform a statistical analysis of our data and observe that dynamic positioning of objects, head rotational speeds and sensitive regions are related to user positions. based on our analysis, we present a CNN (DGaze) model that combines object position sequence, head speed sequence, and saliency features to predict users' position in the position of view. Our model can be applied to anticipate not only real-time positions, but also to look at positions in the near future and achieve better results than the previous method. In terms of actual forecasting, DGaze achieved a 22.0% improvement from the previous method in dynamic scenes and received an improvement of 9.5% in static scenes, based on the use of angular distance as a metric score. We also offer a variant of our model called DGaze_ET, which can be used to predict future positions with higher precision by combining accurate data from the past collected using eye tracking. We further analyze our CNN architecture and check the effectiveness of each component in our model. We apply DGaze to watch contingent and game, and also present the results of the user survey assessment. Targeting against attracting attention: Study on the effectiveness of central and peripheral cues in panoramic videos Anastasia Schmitz (University College London, United Kingdom), Andrew McQuarry (University College London, United Kingdom), Simon Julier (University College London, United Kingdom), Nicola Binetti (University College London, United Kingdom), Anthony Steed (University College London, United Kingdom) Abstract Conference: This study of mixed methods assesses the effectiveness of the use of central arrows and peripheral to draw attention in panoramic videos. The 25 adults wore an eye-tracker head display and were targeted to 14 goals in two videos. There are no significant differences in the number of signals followed, the time it takes to reach and monitor the user's goals, memory and engagement. However, participants' glances have travelled significantly greater distance to targets within the first 500ms after flickering compared to arrows. However, most users prefer the arrow, seeing it as more rewarding. Traditional attention paradigms may not be fully applicable to panoramic videos. A study of the impact of 360° film cuts in the attention of users Carlos Maranes (Universidad de Zaragoza), Diego Gutierrez (Universidad de Zaragoza), Ana Serrano (Universidad de Zaragoza) Abstract: The production of cinematic virtual reality content (VR) is still in its early exploratory phase. A key element in film editing is the use of cutting techniques to seamlessly move from one sequence to another. A major aspect of these techniques is camera control. However, in VR, users can freely explore around them 360°, potentially leading to many different experiences. We perform a systematic analysis of users' viewing behaviour across borders while monitoring 360° videos, and insights that could inform creators about the impact of redundancies in audience behaviour. Comparison of visual guiding approaches for 360°, image-based VR tours Jan Oliver Walgrün (HoroAfronesis, Department of Department State University), Mahda M. Bagher (ChoroPhronesis, 1999, Department of Geography, The Pennsylvania State University), Pejman Sajjadi (HoroAfronesis, Department of Geography, The Pennsylvania State University), Alexander Klippel (HoroFronesis, Department of Geography, The Pennsylvania State University) Abstract Conference: Mechanisms for directing the user visual attention to a particular point of interest play a crucial role in areas such as collaboration VR and AR , cinematic VR, and touring experiences in XR-based education. We report a study in which we compare three different visual guiding mechanisms (arrow, butterfly guide, radar) in the context of 360° imaging-based educational VR tour applications on real sites. A fourth condition without a guidance tool available was added as a baseline. We explore the question: How different approaches compare in terms of target information about participants' experiences and experience scores. SalBiNet360: Forecast of the salyness of 360° images with the local-Global Branched Deep Network Dongwen Chen (South Korean University of Technology, China), Chunmei Qing (South China University of Technology, China), Xiangmin Xu (South China University of Technology, China), Huansheng Zhu (South China University of Technology, China) Abstract: Predicting human visual attention on 360° images is valuable and essential for understanding user behavior. In this document we offer a local-global deep network for predicting 360° images (SalBiNet360). In the global deep sub-network, multiple modules with multiple large-scale presentation modules and a set-top box are used to integrate the functions. Only one multi-show contextual module and single-level decoder are used in the local deep subgrid to reduce duplication of local saliency maps. Finally, the soloist maps are generated by the linear combination of global and local maps of saliency. The experiments illustrate the effectiveness of the proposed framework. Session 4: Avatar - Perception Monday, March 23, 2 p.m. - 3:30 p.m. Tracking 1 (Big Room 1) Thresholds for detecting vertical gains in VR and drone-based teleprompt systems Keigo Matsumoto (University of Tokyo), Eike Langbehn (University of Hamburg), Takuji Narumi (University We examined vertical gains, a new redirection technique that allows us to purposefully manipulate the mapping of a user's physical vertical movements to movements in virtual space and remote space. This approach allows for a natural and more active physical control of a real drone. demonstrate the usability of vertical gains, we have introduced a drone wire and vertical redirection techniques for stretching and brazen use of vr devices are used. We two user studies to study the effective ranges of manipulation and its usability: one study using a virtual environment and one using telethreopieth drone video. Security-Utility Trade-off for Iris Authentication and Eye Animation for Social Virtual Avatars Brendan John (University of Florida), Sophie Jörg (Clemson University), Sanjeev Koppal (University of Florida), Eakta Jain (University of Florida) Journal Abstract: The visual behavior of virtual avatars is crucial for social presence and perceives eye contact during social interactions in Virtual Reality. The virtual reality headset is designed with integrated eye tracking to enable immersive virtual social interactions. This paper shows that infrared cameras used in eye tracking capture images of the eyes that contain the user's iris patterns. Since iris is the gold standard biometric, current technology puts the biometric identity of the user at risk. Our first contribution is a hardware solution based on optical defocus to remove isometric from the flow of eye-tracking images. We characterize the performance of this solution with different internal parameters. Our second contribution is a psychophysical experiment with the same different task that examines users' sensitivity to virtual avatar eye movements when applying this solution. By setting detection thresholds, our findings provide a set of defocus parameters in which a change in eye movement would change in a conversational setting. Our third contribution is a peer-to-peer study to determine the impact of the parameters of the disfocus on perceived eye contact, attention, naturalness and truthfulness of the avatar. Thus, if a user wants to protect their biometric iris, our approach provides a solution that balances biometric protection while preventing their partner from understanding the difference in the user's virtual avatars. This work is the first to develop secure eye tracking configurations for VR/AR/XR applications and motivates future work in the area. Optical design for Avatar-user Coaxial Point of View Telepresence Kei Tsuchiya (University of Electro-Communications), Naoya Koizumi (University of Electro-Communications, JST PRESTO) Abstract Conference: We offer the avatar from VR space to real space with mid-air imaging technology. In this system, micro-mirror plates (MMA) display the mid-air image and optically transfer the camera to capture users from the position of the average aerial image. We assess the performance of image capture and optical specification of mm at. It was confirmed that the detection of faces works correctly on the captured video by adjusting the ISO sensitivity of the camera. In addition, we have developed a teleprompter-action app called dual camera to output the captured video in HMD and control the direction of the camera's view. Andrew Best (University of North Carolina at Chapel Hill, USA), Sahil Narang (University of North Carolina at Chapel Hill, USA), Dinesh Manocha (University of Maryland, USA) Abstract Conference: Introducing a new approach to generating realistic verbal interactions between virtual human agents and user avatars in shared, interactive virtual environments. Sense-Plan-Ask, or SPA, expands its previous natural language planning and processing to allow agents to plan with uncertain information, address questions, and respond to dialogue with other agents and avatars to get the necessary information and fulfill their goals. Agents ask and answer questions. We demonstrate quantitative results by set of simulated indicators and detail the results of a preliminary user survey conducted to assess the plausibility of virtual interactions generated by SPA. Comparing the quality of highly realistic digital people in 3DoF and 6DoF: volumetric video case study Shishir Subramanyam (Centrum Wiskunde & Informatica), Jie Li (Centrum Wiskunde & Informatica), Irina Viola (Centrum Wiskunde and Informatica), Pablo Cesar (Centrum Wiskunde & Informatica) Abstract: Dot clouds have emerged as a popular format for real-time 3D reconstructions like people's recovery for social virtual reality. In this study, we evaluated the effect of compression distortions on the visual quality of cloud digital people's point. We compare the performance of the upcoming cloud compression standard with an anchor. The test is conducted in two CONDITIONS for VR observation, which allow 3- and 6 degrees of freedom. To be best, this is the first work that evaluates the quality of dynamic points points in VR. The results show how the content of visual perception tested is influenced and how current datasets may not be sufficient to fully evaluate compression solutions. Monday, March 23, 2 p.m. - 3:30 p.m., Song 2 (Great Room 2) Ryan R. Strauss (Davidson College), Raguram Ramanuhan (Davidson College), Andrew Becker (Bank of America), Tabitha Peck (Davidson College) Journal Abstract: Redirected (RDW) rolls traditionally rely on human-designed logic. However, recent advances in reinforcement training (RL) have produced systems that surpass the human presentation of various control tasks. This article explores the potential of using RL to develop a new rdw steering jet algorithm. Our approach uses RL to train a deep neural network that directly prescribes the gains of rotation, translation and curvature to transform a virtual environment, taking into account the position and orientation in the tracked space. We compare our scientific algorithm with through simulated and real paths. We found that our algorithm intercepted centre-leading roads and found no significant difference in distance travelled on actual roads. We demonstrate that when modeled as a continuous control issue, RDW is a suitable domain for RL and moving forward, our common framework provides a promising path to an optimal RDW steering algorithm. Antong Cao (State Key Laboratory for Virtual Reality Technologies and Systems; Beihang University; Peng Cheng Laboratory, China), Lily Wang (State Key Laboratory for Virtual Reality Technologies and Systems; Beihang University; Peng Cheng Laboratory, China), Yi Liu (State Key Laboratory for Virtual Reality Technologies and Systems; Beihang University; Peng Cheng Laboratory, China), Voyku Popescu (Purdue University) Abstract: In this paper we propose a method of redirecting a feature-guided path that finds and takes into account the visual characteristics of 3D virtual scenes. A collection of independent and view-dependent VE visual features are retrieved and stored in the visual feature map. The navigation path is deformed to fit within the limits of the available physical space by optimizing the mass-spring transition system, according to distortion-sensitive factors derived from the visual function map. A new detail retention rendering algorithm is used to preserve the original visual details as the user navigates VE on the redirect path. Dynamic artificial potential fields for multisers redirected pedestrian Tianyang Dong (Zhejiang University of Technology, China), Xianwei Chen (Zhejiang University of Technology, China),

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(Facebook, UK), Timothy J. Gentle (Facebook, USA), University of Barcelona, Spain) Abstract: When building apps virtual reality have to choose between different configurations of experience. We are expanding the framework for how these factors contribute to the quality of participants' experience in an indicative assessment. We look at four factors that the expressiveness of an avatar. Participants had the opportunity to spend a budget to change factors to improve their quality of experience. A Markov matrix and probabilities of a factor present at a given level are calculated on the final configurations of the participants. We present this work as an extended contribution to evaluating people's reactions to immersive virtual environments. Measuring a person's confidence in a virtual assistant using the physiological sensation in virtual reality Kunal Gupta (University of Auckland, New Zealand), Ryo Hajika (University of Auckland, New Zealand), Yun Suen Pai (University of Auckland, New Zealand), Andreas Duenser (Data61, CSIRO, Australia), Martin Lochner (Data61, CSIRO, Australia), Mark Billingham (University of Auckland, New Zealand) Abstract: Through our research , we report on a new methodology for investigating a user's confidence in hearing aid in a virtual reality search task (VR) based on , at high and low cognitive load and at different levels of agent accuracy. We collected physiological sensory data, subjective data and a behavioral measure of trust. Our results show that our personalized VR environment allows researchers to measure and understand people's confidence in virtual agents using matrices, and both cognitive exertion and agent accuracy play an important role in confidence formation. We discuss the implications of research and guidance for future work. Grzeszkowiak Fabien (INRIA Rennes, France), Babel Marie (INRIA Rennes, France), Brunei Julien (INRIA Rennes, France), Petter Julien (INRIA Rennes, France) Summary: This article explores the use of VR to study human-robot interactions during navigational tasks. In our case, not only human perception is concerned, but also that of the robot, which must be simulated in order to perceive the VR world. The contribution of this document is double. It first provides a technical solution to perform human robot interactions in navigational tasks via VR. We then evaluate a simple interaction task that we reproduce in real and virtual settings to make the first assessment of the importance of biased bias introduced with the use of VR. Session 24: Visual displays - devices 2 Thursday, March 26, 9:00 - 10:30 a.m. Song 1 (Big Room 1) TELLipsoid: Ellipsoid Video Conferencing System Display Accurate Gaze Direction Taro Ichii (Tokyo Institute of Technology, Japan), Hironori Mitake (Tokyo Institute of Technology, Japan), Shoichi Hasegawa (Tokyo Institute of Technology, Japan) Abstract Conference: We offer Telepion, ellipsoid display for the video conferencing system . not only to realise the exact the convenience and identity of the person. The display consists of an ellipsoid screen, a small projector and a convex mirror, in which the mounted spotlight projects the portrait of a distant participant onto the screen using a convex mirror. The portrait was taken from the photos taken from 360 degrees around the participant. The presentation of the look is carried out by designing the 3D model of the eyeballs on a virtual ellipsoid screen. Physically inspired deep light evaluation by homogeneous material object for mixed reality lighting Jinwoo Park (KAIST, Republic of Korea), Hunmin Park (KAIST, Republic of Korea), Sung-eui Yoon (KAIST, Republic of Korea), Woonack Woo (KAIST, Republic of Korea) Journal Abstract: In Mixed Reality (MR), increasing virtual objects consistently with real lighting is one of the key factors that provide a realistic and immersive user experience. To this end, we offer a new method based on deep learning to evaluate high dynamic range (HDR) lighting from one RGB image to a reference object. In order to obtain illumination of the current scene, previous approaches have placed in this scene a special camera that can interfere with the immersion of the user, or analyze the reflected lights from a passive light probe with a specific type of material or known shape. The proposed method does not require any additional attachments or strong preceding signs and is intended to predict illumination from an image of a observed object with a wide range of homogeneous materials and shapes. To solve this unauthorized problem of opposing imaging, three consecutive deep neural networks are used based on physically inspired design. These networks perform end-to-end regression to gradually reduce dependence on material and shape. To cover different conditions, the proposed networks are trained for a large synthetic data set generated by physically based rendering. Finally, reconstructed HDR lighting allows realistic image-based lighting of virtual objects in MR. Experimental results show the effectiveness of this approach compared to state-of-the-art methods. The document also offers some interesting MR applications in indoor and outdoor scenes. Casual Testero: Casual Capture of Stereo Panoramas with Spherical Structure-by-Motion Lewis Baker (University of Ottago, New Zealand), Steven Mills (University of Ottago, New Zealand), Stephanie Zollman (University of Ottago, New Zealand), Jonathan Shover (California Polytechnic University, USA) Abstract: Manual shooting of stereo panoramas involves rotating the camera in a rough circular path to acquire a dense picture of the scene However, most existing pipeline structures of motion fail when trying to reconstruct trajectories due to the small baseline between the We appreciate a spherical motion structure for the reconstruction of manual stereo panoramas. The spherical restriction introduces strong regulation of the motion structure process, making it suitable for the use of stereo panorama shooting with a manual device. We demonstrate the effectiveness of a spherical motion structure for random shooting of high-resolution stereo panoramas and validate the results with a user survey. Measuring the visual latency system by cognitive latency of video surveillance through AR devices Robert Gruen (Microsoft Research), Eyal Ofek (Microsoft Research), Anthony Steed (Microsoft Research, University College London), Ran Gall (Microsoft Research), Mike Sinclair (Microsoft Research), Mar Gonzalez-Franco (Microsoft Research) Abstract Conference: Measuring visual Latency in VR and AR devices is becoming more complex as many of the components will affect others in multiple cycles and ultimately affect human cognitive and sensory perception. In this document, we present a new method based on the idea that the performance of people on a fast motor task will remain constant and that any additional delay will correspond to the latency of the system. We ask users to complete a task in video viewing devices to compare latency. We also calculate the latency of systems using hardware measurements to mark a bench. The results show that measurement through human cognitive performance can be reliable and comparable to hardware measurement. LiveDeep: Online Viewport Live Virtual Reality Predictions, streaming using Deep Learning Xiangdong Feng (Rutgers University, USA), Yao Liu (SUNY Binghamton, USA), Shen Vee (Rutgers University, USA) Abstract: This paper introduces a new approach to predicting visual port for live VR streaming to reduce bandwidth consumption. We offer a VR streaming lifelong approach to deep learning, namely LiveDeep, to create an online model for predicting visibility and conducting a real-time conclusion. LiveDeep includes (1) an alternative online data collection schedule, labelling, training and conclusions to fit for poor data training; and (2) a mixture of hybrid neural network models to adapt to the inaccuracy caused by a model. We evaluate LiveDeep using a public data set to move virtual reality data, including 48 users and 14 VR videos. Session 25: Follow-up Thursday, March 26, 9am - 10.30am, Song 2 (Big Room 2) Poorly controlled rival training for 3D human poses assessment by Point Clouds Zihao Zhang (Institute of Computer Technology, Chinese Academy of Sciences; University of the Chinese Academy of Sciences), Lei Hu Computing Technologies, Chinese Academy of Sciences; Academy of Sciences), Syaaming Day (Key Laboratory for Human Computer Computing) Chinese Academy of Sciences), Shihong Ia (Institute of Computational Technology, Chinese Academy of Sciences; University of China Academy of Sciences) Journal Abstract: In this work, we study the cloud point-based 3D human posture predicting problem. Previous methods have tried to solve this problem or treat dot clouds as 2D depth maps or as 3D cloud points. However, direct use of a convolution neural network of 2D depth maps can lead to loss of information about 3D space, while it is well established that processing 3D point clouds takes a long time. To solve this problem, instead of relying solely on 3D cloud points or 2D depth maps, we find a way for 3D human posture evaluation by combining the two 2D posing regression methods and 3D deep learning methods. Given the estimated 2D posture, we use hierarchical PoineNet to perform 3D posture regression. It is relatively difficult to collect enough 3D marked data to train a reliable model. That is why we train the regression network in a poorly controlled way of competitive training, using both fully marked data and poorly marked data. Thanks to the adoption of 2D and 3D information, our method can accurately and efficiently calculate a 3D human posture from a single depth map/dot clouds. Experiments on ITOP data and dataset Human3.6M show that our method can outperform state-of-the-art methods. 3D hand Tracking in the presence of excessive motion blur Gabyong Park (KAIST, Republic of Korea), Antonis Argyros (University of Crete and FORT, Greece), Juyoung Lee (KAIST, Republic of Korea), Woonack Woo (KAIST, Republic of Korea) Journal Abstract: We present a sensor-fusion method that uses camera depth and agiroscope to track arm articulation in the presence of excessively fuzzy movements. In the case of slow and smooth hand movements, existing methods assess the hand quite accurately and steadily, despite the challenges associated with the high dimensions of the problem, self-docations, single appearance of hand parts, etc. However, the accuracy of the assessment of the manual position decreases significantly for fast moving hands, because the depth image is strongly distorted due to motion blur. Moreover, when the hands move quickly, the actual posture of the hand is far from what is expected in the previous frame, therefore the assumption of time continuity, on which the tracking methods are relied upon, is invalid. In this article, we track fast-moving hands with a combination of gyroscope and depth camera. As a first step, we calibrate a depth chamber and gyroscope attached to a hand so as to identify their time and pose their offsets. Then, we warn the information for rotating the calibrated with a model-based hierarchical particulate filter. A series of quantitative and qualitative experiments show that the proposed method is presented more accurately and better in the presence of motion blur, movement, compared to state-of-the-art algorithms, especially in the case of very fast hand rotations. Fibar: embedding optical fibers in 3D printed objects for active markers in dynamic projection mapping Daiki Tone (Osaka University), Daisuke Iwai (Osaka University), Shinsaku Hiura (University of Hyogo), Kosuke Sato (Osaka University) Journal abstract: This paper presents a novelty active dynamic projection marker (HR) that emits a lightning-fast model of infrared light (IR) representing its ID. to fabricate a projection with optical fibers that can guide infrared light from LEDs attached to the bottom of the object. The opening of the fiber optic is usually very small; is therefore imperceptible to projection observers and can be placed on a highly curved part of the projection surfaces. Moreover, the working range of our system can be larger than previous methods based on markers, since flashing patterns can theoretically be recognized by a camera placed a wide range of distances from markers. We offer an algorithm for automatic marker placement to spread multiple active markers on the surface of the projection object so that its posture can be reliably calculated using captured images from random directions. We also offer an optimization framework for determining the routes of optical fibers in such a way that collisions of the fibers can be avoided, while minimizing the loss of light intensity in the fibers. Through experiments conducted with three factory-produced objects containing highly curved surfaces, we confirmed that the proposed method can achieve accurate dynamics of dynamic PMs in a significantly wide working range. SPLAT: Spherical localization and tracking in large spaces Lewis Baker (University of Ogo, New Zealand), Jonathan Ventura (California Polytechnic State University, USA), Stefanie Zollmann (University of Ottago, New Zealand), Steven Mills (University of Ottago, New Zealand), Tobias Langlotz (University of Ottago, New Zealand) Abstract: In Augmented Reality (AR) interfaces, it is essential to track camera movement to overlay graphics in the user view. However, in many external scenarios, the user maintains a static position that primarily performs rotations, while simultaneous localization and mapping (SLAM) methods typically require significant translation movement. In this document, we present a SLAM method that combines a spherical movement structure and stable 3D tracking. We show that our method can track more reliably than ORB_SLAM2 in large spaces. We are discussing this issue in the context of the deployment of an AR interface for live events in stadiums and external environments. Deep soft Critiques for markerless volumeless sensor alignment Vladimiro Stertzsenko (Information Research and Technology Thessaloniki, Greece), Alexandros Doumanoglou (Institute of Information Technology, Hellas Research and Technology Centre, Thessaloniki, Greece), Spyridon Thermos (Information Institute of Technology, Hellas Research and Technology Centre, Thessaloniki, Greece), Nikolaos Tsiul (Institute of Information Technology, Hellas Research and Technology Centre, Thessaloniki, Greece), Dimitrios Zappolas (Institute of Information Technology, Hellas Research and Technology Centre, Thessaloniki, Greece), Petros Darras (Institute of Information Technology, Greece), Petros Darras (Institute of Information Technology and Technology), , Hellas Research and Technology Centre, Thessaloniki, Greece) Abstract Conference: In this work we improve the assessment of data matching without marking in order to achieve a more stable and flexible spatial alignment of the multisensor. In particular, we include geometric limitations on a segmentation-based model and bridge the intermediate task of classifying dense with the target assessment of targets. This is achieved by a soft, differentiable forecast analysis that legitimizes segmentation and achieves a higher degree of extra calibration in advanced positioning sensor configurations, while being unlimited from the number of volume capture system sensors. Session 26: Visual rendering on Thursday, March 26, 9:00 AM - 10:30 AM, Track 3 (Studio 1) Underwater Underwater Species Xiaoxu Meng (University of Maryland, College Park), Ruofai Dew (Google LLC), Amitabh Varshney (University of Maryland, College Park) Newspaper Summary: Optimising performance is crucial for a wide range of virtual reality (VR) applications. To reconcile interactive frame rates, they become an important technique for restructuring frames with consistently higher force-display resolutions on their head. Here we present a simple but effective technique to further reduce the cost of fermented rendering using eye dominance – the tendency of the human visual system to prefer the perception of the scene from one eye to the other. Our new eye-dominant approach, guided by the eye eye, which does this, makes the stage at a lower fan level (a higher level) for the dominant eye than not the dominant eye. Compared to traditional foam formations, the EFR can be expected to provide superior rendering while maintaining the same level of visual quality perception. Accelerated stereo rendering with hybrid reprojection rasterization and adaptive ray-weiss Germany), Martin Mishjak (TH Köln, Germany), Arnulf Fuhrmann (TH Köln, Germany), Mark Erich Latoshik (University of Würzburg, Germany) Abstract Conference: This book presents a hybrid rendering system that combines classical rasterization real-time ray tracking to speed up stereoscopic rendering. The system redesigns the The left half of the stereo image pair in the right perspective, using forward network distortion technique and identifying the resulting reprojection errors, which are then effectively solved by adaptive real-time beam tracking. The system achieves a significant increase in performance, has a negligible impact on quality and is suitable even for higher rendering solutions. The angularly dependent on spatial resolution in virtual reality shows Ryan beams (Food and Drug Administration, USA), Brendan Collins (Food and Drug Administration, USA), Andrea S. Kim (Food and Drug Administration, USA), Aldo Badano (Food and Drug Administration, USA) Abstract: We compare two methods for characterizing angular dependence of spatial resolution in displays mounted on the head of virtual reality (HMDs) by measuring the line propagation response (LSR) in the field of vision (FOV) of the device. Multi-scale simulation method of liquid with Trapped Air under a particle-based framework Siniu Liu (University of Science and Technology Beijing, China), Ben Wang (University of Science and Technology Beijing, China), Xiaojuan Banya (University of Science and Technology Beijing, China) Abstract Conference: In this book we offer a multi-scale particle-based simulation method to achieve a realistic and effective air-liquid simulation. A uniform generation rule is available depending on kinetic energy and the difference in speed between fluid particles. Then two dynamic speed-based models are created for different dimensions of air materials respectively. Brown movement of small air materials is achieved by schlik random function. The interaction and transport of air between large air materials is achieved by a reverse diffusion equation and a new function of the high-end core. Experimental results show that the proposed method can improve the fidelity and richness of fluid simulation. Where to show? How interface position affects comfort and time to switch tasks on Glanceable interfaces Samat Imamov (Virginia Tech, USA), Daniel Monzel (Virginia Tech, USA), Wallace Lages (Virginia Tech, USA) Abstract Conference: Critical solution when designing screens for view information is the place of content. However, no study has been done to systematically evaluate the world-locked content position, given both cognitive and physiological limitations. We created a scenario that mimics the context shift between a real global task and an information display. Our results show that the time to change discomfort and context increases as the information is displayed far from the position of the task. We also found that medium-range content, although they were also faster with long-range content. Session 27: Audio Thursday, March 26, 11:00 - 12:30 PM, Track 1 (Big Room 1) Superhuman Hearing - - Prototyping artificial hearing: A case study of interactions and sound beaming Michel Geronazzo (Aalborg University, Denmark), Luis S. Vieira (Khora VR, Denmark), Niels Christian Nilsson (Aalborg University, Denmark), Jesper Udesen (GN Audio A/S), Stefania Serafin (Aalborg University, Denmark) Journal Abstract: Directivity and gain in microphone systems for hearing aids or hearing aids allow users to enhance in acoustic information from the source of interest. This function is called acoustic radiation formation. This study aimed to improve user interaction with radiation formation through a virtual prototype approach in immersive virtual environments (RE). Eighteen participants participated in experimental sessions consisting of a calibration procedure and a selective hearing task for pairing voice calls. Eight simultaneous speakers are placed in one aechoic environment in two virtual reality (VR) scenarios. The scenarios are a purely virtual scenario and a realistic 360 degree audio-visual recording. Participants were asked to find an individual optimal parameterization for three different virtual beam beams: (i) a guided head, (ii) an eye-guided, and (iii) a new interaction technique called dual beamogener, where the guide head is combined with additional manually directed radiation formation. None of the participants was able to complete the task without a virtual radiation machine (i.e. in normal hearing mode) due to the high complexity introduced by the design. However, participants were able to correctly pair all speakers using all three suggested interaction metaphors. The provision of superhuman auditory abilities in the form of acoustic beam-ray forms guided by head movements leads to statistically significant improvements in pairing time, suggesting that the task is the relevance of interaction with multiple points of interest. Stage audio playback through deep acoustic analysis Genyu Tang (University of Maryland), Nicholas J. Bryan (Adobe Research), Dingzeyu Li (Adobe Research), Timothy R. Langlois (Adobe Research), Dinesh Manocha (University of Maryland) Journal Abstract: We present a new method for capturing the acoustic characteristics of rooms in the real world using raw materials devices, and use the captured features to generate similar sources with virtual models. Given the captured audio and approximate geometric pattern of a room in the real world, we present a new learning-based method to assess its properties of acoustic materials. Our approach is based on deep neural networks that calculate the time of reverberation and alignment of the room from the recorded audio. These estimates are used to calculate the properties of the reverberation of the premises using a new material optimization target. We use the expected characteristics of the acoustic material for audio audio geometric sound and highlight the presentation of very real scenarios. We are also conducting a user survey to assess the similarity of our recorded and our audio. EarVR: Using ear bites in virtual reality for deaf and hearing-impaired people Mohammadreza Mirzai (Vienna University of Technology, Austria), Peter Kahn (Vienna University of Technology, Austria), Hannes Kaufmann (Vienna University of Technology, Austria) Abstract: Virtual reality (VR) has great potential to improve the skills of people with deaf and hard-to-hear people. Most VR apps and devices are designed for people without hearing problems. Therefore, DHH individuals have many limitations when using VR. Adding special features to a VR environment, such as subtitles or haptic devices, will help them. Previously, it was necessary to design a special VR environment for DHH individuals. We present and evaluate a new prototype called EarVR, which can be mounted on any computer or mobile VR Head-Mounted Display (HMD). EarVR analyzes 3D sounds in a VR environment and finds the direction of the sound source closest to the user. It notifies the user of the direction of sound using two vibromotors placed on the user's ears. EarVR helps DHH individuals complete sound VR tasks in any VR app with 3D audio and an option to turn off background music. Therefore, DHH individuals can use all VR applications with 3D audio, not just those applications designed for them. Our user study shows that DHH participants were able to complete a simple VR task significantly faster with EarVR than without. The completion time of DHH participants was very close to the participants without hearing problems. Also, it shows that DHH participants were able to complete a complex VR task with EarVR, while without it, they could not complete the task even once. Finally, our qualitative and quantitative assessment among DHH participants shows that they prefer to use EarVR and encourages them to use VR technology more. Outdoor sound distribution based on adaptive FDTD-PE Shiguang Liu (Tianjin University), Jin Liu (Tianjin University) Abstract Conference: We offer an adaptive FDTD-PE method to simulate sound propagation in 3D scenes taking into account atmospheric inhomogeneity and the influence of the earth. In the simulation, the ground is considered a porous environment of a certain thickness and the stage is categorized into several 2D planes. In addition, a new encoding method is designed to process sound pressure data through the functional connection. Finally, an effective method of displaying sound with this coding representation is developed to perform localization in the frequency domain. Experiments have shown that our method can realistically simulate the propagation of the sound of with much higher speed and lower memory. Session 28: 28: : Safety, Education, Architecture, Thursday Traffic Control, March 26, 11 a.m. - 12:30 p.m. Trail 1 (Big Room 1) Exploring eye visualization techniques to identify distracted students from the educational VR Yitoshree Rahman (University of Louisiana at Lafayette, Lafayette, Louisiana, United States), Sarker Monojit Ashish (University of Louisiana at Lafayette, Lafayette, Louisiana), Fisher (University of Louisiana, Lafayette, Louisiana, USA), Ethan Charles Bruce (University of Louisiana at Lafayette, Lafayette, Louisiana, Louisiana, United States), Aaron K. Kulschersch (University of Louisiana at Lafayette, Lafayette, Louisiana, USA), Christo Videodeath with built-in eye trackers can be used in VR-based education, in which a live teacher leads a group of students. Eye tracking can allow for a better understanding of students' activities and behavior. For a real-time look, the teacher's VR environment can show the student's gaze. These visualizations will help identify students who are confused/distracted, and the teacher can better direct them to focus on important subjects. We present six eye visualization techniques for a teacher's perspective in VR and present a user survey to compare these techniques. Presence, mixed reality and risk-related behavior: Study of safety measures Sogand Hasanazadeh (Virginia Tech, USA), Nicolas Polis (Virginia Tech, USA), Jesus M. de la Garza (Clemson University, United States) Journal Abstract: Immersive environments have been successfully applied to a wide range of safety trainings in high-risk domains. However, very few studies have used these systems to assess the risk behaviour of construction workers. In this study, we examined the feasibility and usefulness of providing passive haptics in a mixed reality environment to cover the behaviour of risk-takers, identify at-risk workers and propose injury prevention measures to counter excessive risk-taking and risk-compensating behaviour. In the mixed environment in a cave-like system, our subjects installed herpes zoranbi on the (physical) sloping roof of a (virtual) two-storey apartment building in the morning in a suburban area. Through this controlled, intra-site experimental project, we exposed each object to three experimental conditions by manipulating the level of safety interference. Subjective worker reports, physiological signals, psychophysical reactions and reaction behaviors are considered promising measures of presence. The results show that our mixed reality environment is an appropriate platform for triggering behavioural changes in various experimental risk perception and risk-taking of workers in risk-free conditions. These results demonstrate the value of immersive technology for the study of natural human factors. Health and Safety of VR Use by Children in Educational Case Robert Rausenberger (Phoenix Consumer Research Center, Exponent, Inc.), Brandon Barakat (Phoenix Consumer Research Center, Exponent, Inc.) Conference Summary: This study explores the potential health and safety effects of children's use of short-term virtual reality (VR) in an educational scenario. Thirty children participants (age 10-12 years) used VR for 30 minutes daily on five consecutive days. Various optometric, psychophysical and self-reflective comfort measures were collected. There is no empirical evidence that short-term use of VR in an educational environment by children aged 10 to 12 years results in adverse visualizations, spatial representation or results, or that it causes undue nausea, oculomotor discomfort or disorientation. Design and evaluation of an air traffic control support tool with 2D and 3D visualizations Gernot Rottermanner (St. University of Applied Sciences, St. Mylen Craigier (University of Applied Sciences St. Puelten, St. Poelten, Austria), Marcus Wagner (University of Applied Sciences Poelten, St. Poelten, Austria), Michael Iber (University of St. Poeln, St. Pölsen, Austria), Karl-Herbert Rokitansky (University of Salzburg, Institute of Computer Science , Aeropore research, Salzburg, Austria), Kurt Esbacher (University of Salzburg, Institute of Computer Science, Space Studies, Salzburg, Austria), Volker Grantz (Ofen AGIS , Vienna, Austria), Volker Settgast (Fraunhofer Austria Research GmbH, Vienna, Austria), Peter Judmaier (University of Applied Sciences St. Poelten, Austria) Abstract: Air Traffic Control Officers (ATCOs) are specialized workers responsible for monitoring and guiding aircraft in their airspace. This task is highly visual and is mainly supported by 2D visualizations. In this document, we developed and evaluated an application for visualization of air traffic both in orthographic (2D) and in perspective (3D). A user survey was then carried out to compare these two types of representations in terms of awareness, workload, productivity and user acceptance. The results showed that the 3D view resulted in both a higher level of awareness and less load than the 2D view. However, this implementation is not in line with the opinion of the Study in the field. Desktop comparison, immersive virtual reality and real field trips for the education of STEM Jiayan Zhao (State University of Pennsylvania, USA), Peter LaFemina (State University of Pennsylvania, USA), Julia Carr (State University of Pennsylvania, USA), Peimman Sajjadi (The Pennsylvania State University, USA), Jan Oliver Walgrün (The Pennsylvania State University, USA), Alexander Klippel (Pennsylvania State University, USA) Abstract Conference : With immersion in virtual reality (iVR) the entry of basic, virtual field excursions (VFTs) are increasingly considered an effective form of training in STEM disciplines such as geosciences. However, few studies have studied the effects of VFTs in technology-based STEM education. We report a study that divides an introductory geoscience course into three groups, with the first two groups experiencing CNG on the desktop or in iVR, while the third group went on an actual field trip. Our findings show positive learning effects of VFTs and provide evidence that VFT geology does not need to be limited to iVR settings. Session 29: AR - Perception Thursday, March 26, 11:00 AM - 12:30 PM, Track 3 (Studio 1) ARCHIE: User-focused framework for testing augmented reality apps at Wild Sarah Lehman (Temple University), Haibin Ling (Stony Brook University), Chiu Tan (Temple University) Abstract: Introducing ARCHIE, a framework for testing augmented reality apps in the wild. ARCHIE collects user data submission data and on-site system state to help developers identify and debug issues important for testers. It also supports testing multiple versions of apps (profiles) in one rating, prioritizing those versions that the tester finds more attractive. We implemented four test cases and used them to look at ARCHIE overhead costs and context switching costs. We demonstrate that ARCHIE does not provide significant costs for AR applications and introduces a top 2% cost processing when switching between large groups of test accounts. The paradox of realismity For users with scaling and down in a virtual environment Matti Pouke (University of Oulu, Finland), Katherine J. Minnau (University of Oulu, Finland), Timo Oyala (University of Oulu, Finland), Steven M. LaValle (University of Oulu, Finland) Abstract: This document identifies a new phenomenon: when users interact with simulated objects in a virtual environment where the user is much smaller than usual , there is a mismatch between the expected and correct convergence of physics on this scale. We explored perceived realism in a virtual reality experience in which the user was 10th, and four objects performed a task to interact with objects in two physical simulations. In one objects behave exactly according to physics, which would be correct on this reduced scale. In the other condition, objects behave as if there was no scaling. We found that a significant majority of consumers preferred the latter condition. The role of distance viewing and feedback on judgments on synonyms in augmented reality Holly Gagnon (University of Utah, USA), Dunn On (Vanderbilt University, USA), Keith Heiner (University of Utah, USA), Janine Stefanucci (University of Utah, USA), Sarah Kram-Reger (University of Utah, USA), Bobby Bodenheimer (University of Vanderbilt, USA) Abstract: The effectiveness of Augmented Reality (AR) that they can act on virtual objects as if they are real. We looked at the effects of visual distance (associated with virtual features observed in the field of visibility) and verbal feedback on observers' judgment of going through an AR opening using Microsoft HoloLens. Passing through the estimates is closer to the actual width of the shoulder when viewed at close range compared to a more distant viewing point. Verbal feedback reduces the error of attempts at the distance. The results have implications for ways to improve the accuracy of court decisions to grant permits in AR. Fayu Lu (Virginia Tech, United States), Shakiba Babari (Virginia Tech, United States), Lee Lisle (Virginia Tech, United States), Yuan Li (Virginia Tech, USA), Doug Bowman (Virginia Tech, USA) Abstract: Enriched Realities Worn Out (AR HWDs) have the potential to help personal computers and obtain daily information. In this study, we propose an interaction analysis with a view to accessing information in AR HWDs. In a short analysis, secondary information is located on the periphery of vision to remain unobtrusive and can be accessed with a quick glance when needed. We have proposed two new hands-free interfaces under the paradigm, using head-turning or a glance to access information. We evaluated them in two dual task scenarios together with hud basic technique. Influence the perspective of dynamic tasks in virtual reality navy (University of Bath, UK), Emonn O'Neill (University of Bath, UK) Abstract: Users can increasingly navigate and perform tasks in a virtual environment (VE). These movements and tasks are usually presented in the IC using either a first-person perspective (1HR) or a third-party perspective (3PP). In virtual reality (VR), 1PP is almost universally used. 3PP may be presented as self-centered or allocentric. However, there is little empirical evidence that may be better suited to dynamic tasks in particular. This article compares the use of 1PP, 3PP and allocentric 3PP for dynamic tasks in VR. Our results show that 1PP provides the best spatial perception performance of several dynamic tasks. This advantage is less pronounced as the task becomes more dynamic.

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